Developing Natural Full-body Motion Synthesis in Virtual Humans

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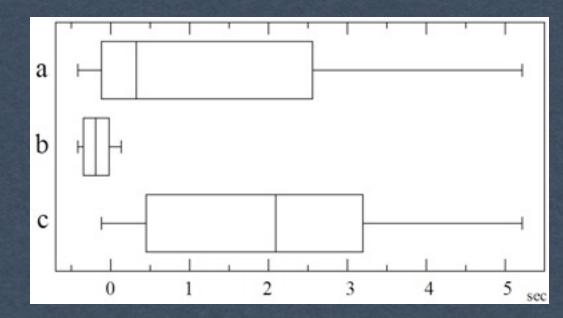
Background



- The system under development is a two-phase immersive virtual reality training program with interactive virtual human agents ^[1].
- The system uses realistic, parametrized gestures in various contexts.
- Phase I (modeling): Experts model needed gestures/actions via demonstration using motion capture hardware.
- Phase II (training): Captured motions are reused to train apprentice users.

Study I – Gaze Model

- Gaze behavior is an important non-verbal communication channel for effective full-body motion synthesis.
- We focus on analyzing gaze behaviors in demonstrative tasks.
- Time stamps of key gaze events are annotated.
- Temporal parameters of gaze behaviors are analyzed and modeled.
- 1. Temporal delay (Δt) between action stroke point and starting of gaze-at-viewer event.



- 2. Correlations between duration of gaze-atviewer and viewer positions.
- 3. Gradual decline of gaze-at-viewer durations.

Motion Capture



Horizontal Target Plane

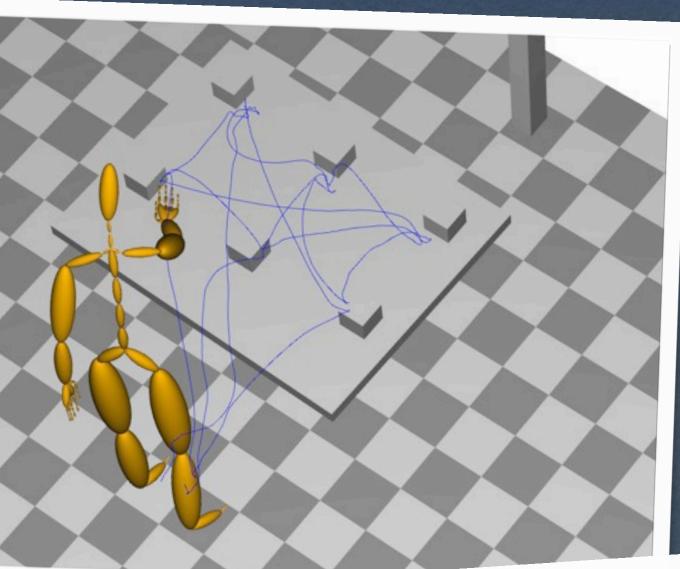


Vertical Target Plane

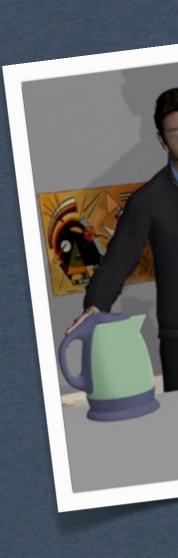
 α - relative standing location for the viewer in respect to target object β - relative standing location for the agent in respect to target object

^[1] Interactive Motion Modeling and Parameterization by Direct Demonstration, C. Camporesi, Y. Huang and M. Kallmann, Intelligent Virtual Agents (IVA), 2010 ^[2] Motion Parameterization with Inverse Blending, Y. Huang and M. Kallmann, The Third International Conference on Motion in Games (MIG), 2010 ^[3] Gesture Variants and Cognitive Constraints for Interactive Virtual Reality Training Systems, S. Huette, Y. Huang, M. Kallmann, T. Matlock and J. L. Matthews, IUI 2011

Motion Analysis

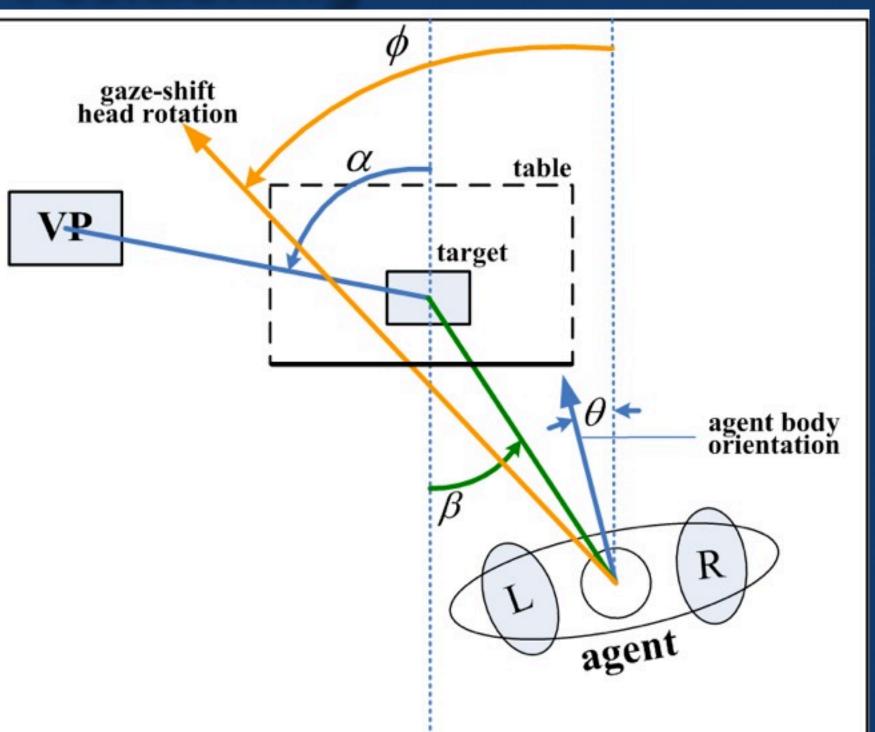


- gesture.



• Top: hand trajectory of captured pointing motion. • Bottom: annotation application showing gaze phase-plane and reconstructed environment.

Study II – Body Positioning



 Θ - body orientation of the agent

 ϕ - maximum head rotation during gaze-at-viewer





• These early findings on gaze modeling, body positioning and locomotion-action coordination will inform the design and utility of interactive training and educational applications with virtual humans ^[3], and shape the future work in this domain.





Study III – Coordination

• Upper-body actions and gestures are parametrized with *Inverse Blending* ^[2].

• Lower-body walk and stepping sequence is generated with either Motion Graphs or a locomotion planner.

• The coordination of upper- and lower- motions is critical for generating human-like movements.

• The focus is on the short blending window at the end of locomotion and beginning of upper-body action/





User Evaluation